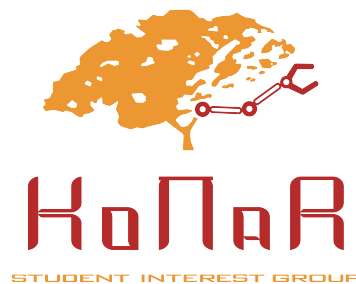


RULES OF ROBOTIC TOURNAMENT

“Robotic Arena 2017”

BALLUFF LineFollower Drag

“KoNaR” Student Interest Group
Faculty of Electronics
Wrocław University of Science and Technology



Section I

General

§ 1

1. This document regulates rules of the tournament in category “BALLUFF LineFollower Drag”.

Section II

Robot Specification

§ 2

1. Robots can't be pre-built, commercial construction.
2. Robots must fit on a standard A4-size paper.
3. Height of robots is not limited.
4. Weight of robots is not limited.
5. Communication with robots during matches is forbidden.
6. Disabling robots remotely is an exception from the point above.

§ 3

1. Robots must be fully autonomous.
2. Robots must be designed so that it can be run at the mark given by the judge.
3. Robots can be equipped with ”EDF” (Electric Ducted Fan) or other active devices for better adhesion.

4. Robots functionality cannot be dependent on varying environment during tournament, such as lighting (from dusk to bright reflectors), smoke, loud music or laser effects. The show may be lit by regular lightbulbs, halogens, energy saving lightbulbs, fluorescent lamps, LEDs and other lightsources common in households. Organizers have no control over street lighting near windows of the building. During the show it will be forbidden to use camera flashes and other intense light.

Section III

Route Specification

§ 4

1. Route is defined by black line (with width up to 2 cm) placed on a white background.
2. Surface with route can be built from a many connected components. Any set offs on the components' connection will be possibly eliminated.
3. The route is approximately a straight line with length from 15 to 30 m.
4. The route includes breaking zone with length from 5 to 10 m.
5. The route can't be a closed loop.
6. The route can't include right angle or crossroad.
7. The route can't have hills.
8. The route can't have breaks in line, bifurcations or any obstacles.
9. The route area is limited by a rectangle, which fully includes the route. The rectangle will be defined along with the selection of the exact route run.
10. The gates (for time measurement) have to be placed at two sides at least 170mm away from line.

Section IV

Competition

§ 5

1. Competition will be conducted in two stages:
 - (a) Elimination phase,
 - (b) Finals.
2. Matches in elimination phase will be held based on the schedule given by the referee.
3. 8 best constructions from elimination phase will take part in finals.
4. Matches in finals will be held based on the schedule given by the referee.
5. As a result of referee's decision, there can be only final stage. Therefore:
 - (a) Each robot can take part in final stage (only after succesful registration process)
 - (b) Matches in finals will be held based on the schedule given by the referee.
6. Each phase results announcement will occur after finishing the phase.

Section V

Winner Selection Rules

§ 6

1. Before start of the ride, the participants are placing the robots on the start line as instructed by the referee.
2. Robots are started on the mark of a judge.
3. The false start happens when robot exceed start line before mark of a judge.
4. First false start restarts the ride.
5. Second false start makes ride as unfinished.
6. Leaving the route by the robot occurs, when the robot's contour gets away from route.
7. Each robot, after leaving the route, have to get back on the route by itself.
8. If the robot gains the advantage by leaving the route, the ride is getting unfinished.
9. The referee decides, if the robot gained the advantage.
10. If the robot leaves the route area, the ride is getting unfinished.

§ 7

1. Time of overcome distance is the time counted from passing the start line to moment of passing the finish line.
2. Passing the start/finish line means that any component of the robot has passed it.
3. Time of overcome distance is measured by gate or by the referee with stopwatch (if the gate will crash).
4. The gate has at least 1 sensor, placed 1cm above the route's surface.
5. It is recognized that the robot has passed the finish line only if any of the sensors will notice it.
6. There is a 3 mins limit for passing the route.
7. If the ride is longer than 3 mins, it's getting unfinished.

§ 8

1. If the phase is taking place on 1 track, the shortest time of ride is taken into consideration in final classification of the phase.
2. If the phase is taking place on 2 tracks, the biggest amount of the points (obtained in duels of randomly selected pairs of robots) is taken into consideration in final classification of the phase.
3. Final classification of the phase is determined on the rules defined in this paragraph.